

### Actions

*mc: move clockwise*

*mcc: move counterclockwise*

*puc: pick up coffee*

*dc: deliver coffee*

*pum: pick up mail*

*dm: deliver mail*

### Locations:

*cs: coffee shop*

*off: office*

*lab: laboratory*

*mr: mail room*

### Feature values

*rhc: robot has coffee*

*swc: Sam wants coffee*

*mw: mail waiting*

*rhmc: robot has mail*

